# Average optimal strategies in Markov games under a geometric drift condition * 

Heinz-Uwe Küenle


#### Abstract

Zero-sum stochastic games with the expected average cost criterion and unbounded stage cost are studied. The state space is an arbitrary Borel set in a complete separable metric space but the action sets are finite. It is assumed that the transition probabilities of the Markov chains induced by stationary strategies satisfy a certain geometric drift condition. It is shown that the average optimality equation has a solution and that both players have optimal stationary strategies.


1991 Mathematics Subject Classification: 91A15
Keywords and phrases: Markov games, Borel state space, average cost criterion, geometric drift condition, unbounded costs

## 1 Introduction

In this paper two-person stochastic games with the expected average cost criterion are studied. The state space is a standard Borel space, that is, an arbitrary Borel set in a complete separable metric space. The action sets of both players are finite. Such a stochastic game can be described in the following way: The state $x_{n}$ of a dynamic system is periodically observed at times $n=1,2, \ldots$. After an observation at time $n$ the first player chooses an action $a_{n}$ from the action set $\boldsymbol{A}\left(x_{n}\right)$ and afterwards the second player chooses an action $b_{n}$ from the action set $\boldsymbol{B}\left(x_{n}\right)$ dependent on the complete history of the system at this time. The first player must pay cost $k^{1}\left(x_{n}, a_{n}, b_{n}\right)$, the second player must pay

[^0]$k^{2}\left(x_{n}, a_{n}, b_{n}\right)$, and the system moves to a new state $x_{n+1}$ in the state space $\mathbf{X}$ according to the transition probability $p\left(\cdot \mid x_{n}, a_{n}, b_{n}\right)$.

Stochastic games with Borel state space and average cost criterion are considered by several authors. Related results are given by Maitra and Sudderth [7], [8], [9], Nowak [13], Rieder [15] and Küenle [6] in the case of bounded costs (payoffs). The case of unbounded payoffs is treated by Nowak [14] and Küenle [4]. The assumptions in this paper concerning the transition probabilities are related to Nowak's assumptions: Nowak assumes that there is a Borel set $C \in \mathbf{X}$ and for every stationary strategy pair $\left(\pi^{\infty}, \rho^{\infty}\right)$ a measure $\mu$ such that $C$ is $\mu$-small with respect to the Markov chain induced by this strategy pair. We assume that $C$ is only a $\mu$-petite set with respect to a resolvent of this Markov chain; as against this, we demand that $\mu$ is independent of the corresponding strategy pair. (For the definition of "small sets" and "petite sets" see [10].)

The paper is organised as follows: In Section 2 the mathematical model of Markov games is presented. Section 3 contains the assumptions on the transition probabilities and on the stage costs, and also some preliminary results. In Section 4 we study the expected average cost of a fixed stationary strategy pair. We show that the Poisson equation has a solution. In Section 5 we prove that the average cost optimality equation has a solution and both players have optimal stationary strategies.

## 2 The Mathematical Model

In this section we introduce the mathematical model of the stochastic game considered in this paper.

## Definition 2.1

$\mathcal{M}=\left(\left(\mathbf{X}, \sigma_{\mathbf{X}}\right),\left(\mathbf{A}, \sigma_{\mathbf{A}}\right), \boldsymbol{A},\left(\mathbf{B}, \sigma_{\mathbf{B}}\right), \boldsymbol{B}, p, k^{1}, k^{2}, \mathbf{E}, \mathbf{F}\right)$ is called a Markov game if the elements of this tuple have the following meaning:

- $\left(\mathbf{X}, \sigma_{\mathbf{X}}\right)$ is a standard Borel space, called the state space.
- $\mathbf{A}$ is a countable set and $\sigma_{\mathbf{A}}$ is the power set of $\mathbf{A} . \boldsymbol{A}(x) \in \mathbf{A}$ denotes a finite set of actions of the first player for every $x \in \mathbf{X}$. $\mathbf{A}$ is called the action space of the first player and $\boldsymbol{A}(x)$ is called the admissible action set of the first player at state $x \in \mathbf{X}$.
- $\mathbf{B}$ is a countable set and $\sigma_{\mathbf{B}}$ is the power set of $\mathbf{B} . \boldsymbol{B}(x) \in \mathbf{B}$ denotes a finite set of actions of the second player for every $x \in \mathbf{X}$. $\mathbf{B}$ is called the action space of the second player and $\boldsymbol{B}(x)$ is called the admissible action set of the second player at state $x \in \mathbf{X}$.
- $p$ is a transition probability from $\sigma_{\mathbf{X} \times \mathbf{A} \times \mathbf{B}}$ to $\sigma_{\mathbf{X}}$, the transition law.
- $k^{i}, i=1,2$, are $\sigma_{\mathbf{X} \times \mathbf{A} \times \mathbf{B}}$-measurable functions, called stage cost functions.
- Let $\mathbf{H}_{n}=(\mathbf{X} \times \mathbf{A} \times \mathbf{B})^{n} \times \mathbf{X}$ for $n \geq 1, \mathbf{H}_{0}=\mathbf{X} . h \in \mathbf{H}_{n}$ is called the history at time $n$.
A transition probability $\pi_{n}$ from $\sigma_{\mathbf{H}_{n}}$ to $\sigma_{\mathbf{A}}$ with
$\pi_{n}\left(\boldsymbol{A}\left(x_{n}\right) \mid x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right)=1$ for all $\left(x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right) \in \mathbf{H}_{n}$ is called a decision rule of the first player at time $n$.
A transition probability $\rho_{n}$ from $\sigma_{\mathbf{H}_{n} \times \mathbf{A}}$ to $\sigma_{\mathbf{B}}$ with
$\rho_{n}\left(\boldsymbol{B}\left(x_{n}\right) \mid x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right)=1$ for all $\left(x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right) \in \mathbf{H}_{n}$ is called a decision rule of the second player at time $n$.
A decision rule of the first [second] player is called Markov iff a transition probability $\tilde{\pi}_{n}$ from $\sigma_{\mathbf{H}_{n}}$ to $\sigma_{\mathbf{A}}$ [ $\tilde{\rho}_{n}$ from $\sigma_{\mathbf{H}_{n}}$ to $\left.\sigma_{\mathbf{B}}\right]$ exists such that $\pi_{n}\left(\cdot \mid x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right)=\tilde{\pi}_{n}\left(\cdot \mid x_{n}\right)$ $\left[\rho_{n}\left(\cdot \mid x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right)=\tilde{\rho}_{n}\left(\cdot \mid x_{n}\right)\right]$ for all $\left(x_{0}, a_{0}, b_{0}, \ldots, x_{n}\right) \in$ $\mathbf{H}_{n} \times \mathbf{A}$. (Notation: We identify $\pi_{n}$ as $\tilde{\pi}_{n}$ and $\rho_{n}$ as $\tilde{\rho}_{n}$.)
$\mathbf{E}$ and $\mathbf{F}$ denote non-empty sets of Markov decision rules.
A decision rule of the first [second] player is called deterministic if a function $e_{n}: \mathbf{H}_{n} \rightarrow \mathbf{A}\left[f_{n}: \mathbf{H}_{n} \rightarrow \mathbf{B}\right]$ exists such that $\pi_{n}\left(e_{n}\left(h_{n}\right) \mid h_{n}\right)=1$ for all $h_{n} \in \mathbf{H}_{n}\left[\rho_{n}\left(f_{n}\left(h_{n}\right) \mid h_{n}\right)=1\right.$ for all $\left.\left(h_{n}\right) \in \mathbf{H}_{n}\right]$.

A sequence $\Pi=\left(\pi_{n}\right)$ or $P=\left(\rho_{n}\right)$ of decision rules of the first or second player is called a strategy of that player.
Strategies are called deterministic, or Markov iff all their decision rules have the corresponding property.
A Markov strategy $\Pi=\left(\pi_{n}\right)$ or $P=\left(\rho_{n}\right)$ is called stationary iff $\pi_{0}=\pi_{1}=\pi_{2}=\ldots$ or $\rho_{0}=\rho_{1}=\rho_{2}=\ldots$. (Notation: $\Pi=\pi^{\infty}$ or $P=\rho^{\infty}$.) We assume in this paper that the sets of all admissible strategies are $\mathbf{E}^{\infty}$ and $\mathbf{F}^{\infty}$. Hence, only Markov strategies are allowed. But by means of dynamic programming methods it is also possible to get corresponding results for Markov games with larger sets of admissible strategies. If $\mathbf{E}$ and $\mathbf{F}$ are the sets of all Markov decision rules
(in the above sense) then we have a Markov game with perfect (or complete) information. In this case the action set of the second player may depend also on the present action of the first player. If $\mathbf{E}$ is the set of all Markov decision rules but $\mathbf{F}$ is the set of all Markov decision rules which do not depend on the present action of the first player then we have a usual Markov game with independent action choice. Let $\Omega:=\mathbf{X} \times \mathbf{A} \times \mathbf{B} \times \mathbf{X} \times \mathbf{A} \times \mathbf{B} \times \ldots$ and $K^{i, N}(\omega):=\sum_{j=0}^{N} k^{i}\left(x_{j}, a_{j}, b_{j}\right)$ for $\omega=\left(x_{0}, a_{0}, b_{0}, x_{1}, \ldots\right) \in \Omega, i=1,2, N \in \mathbb{N}$. By means of the Ionescu-Tulcea Theorem (see, for instance, [11]), it follows that there exists a suitable $\sigma$-algebra $\mathcal{F}$ in $\Omega$ and for every initial state $x \in \mathbf{X}$ and strategy pair $(\Pi, P), \Pi=\left(\pi_{n}\right), P=\left(\rho_{n}\right)$, a unique probability measure $\mathrm{P}_{x, \Pi, P}$ on $\mathcal{F}$ according to the transition probabilities $\pi_{n}, \rho_{n}$ and $p$. Furthermore, $K^{i, N}$ is $\mathcal{F}$-measurable for all $i=1,2, N \in \mathbb{N}$. We set

$$
\begin{equation*}
V_{\Pi P}^{i, N}(x)=\int_{\Omega} K^{i, N}(\omega) \mathrm{P}_{x, \Pi, P}(d \omega) \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\Phi_{\Pi P}^{i}(x)=\liminf _{N \rightarrow \infty} \frac{1}{N+1} V_{\Pi P}^{i, N}(x) \tag{2.2}
\end{equation*}
$$

if the corresponding integrals exist.

## Definition 2.2

A strategy pair $\left(\Pi^{*}, P^{*}\right)$ is called a Nash equilibrium pair iff

$$
\begin{aligned}
& \Phi_{\Pi^{*} P^{*}}^{1} \leq \Phi_{\Pi P^{*}}^{1} \\
& \Phi_{\Pi^{*} P^{*}}^{2} \leq \Phi_{\Pi^{*} P}^{2}
\end{aligned}
$$

for all strategy pairs $(\Pi, P)$.
In this paper we will consider especially zero-sum Markov games, that means $k^{1}=-k^{2}$. In this case we call a Nash equilibrium pair also an optimal strategy pair. We set $k:=k^{1}, V_{\Pi P}^{N}:=V_{\Pi P}^{1, N}, \Phi_{\Pi P}:=\Phi_{\Pi P}^{1}$.

## 3 Assumptions and Preliminary Results

In this paper we use the same notation for a substochastic kernel and for the "expectation operator" with respect to this kernel, that means: If $\left(\mathbf{Y}, \sigma_{\mathbf{Y}}\right)$ and $\left(\mathbf{Z}, \sigma_{\mathbf{Z}}\right)$ are standard Borel spaces, $v: \mathbf{Y} \times \mathbf{Z} \rightarrow \mathbb{R}$ a
$\sigma_{\mathbf{Y} \times \mathbf{Z}}$-measurable function, and $q$ a substochastic kernel from ( $\mathbf{Y}, \sigma_{\mathbf{Y}}$ ) to ( $\mathbf{Z}, \sigma_{\mathbf{Z}}$ ) then we put

$$
q v(y):=\int_{\mathbf{Z}} q(d z \mid y) v(y, z) \text { for all } y \in \mathbf{Y}
$$

if this integral is well-defined.
Furthermore, we define the operator $T$ by

$$
T u=k+p u
$$

for all $\sigma_{\mathbf{X}}$-measurable $u: \mathbf{X} \rightarrow \mathbb{R}$ for which $p u$ exists, that means,

$$
T u(x, a, b)=k(x, a, b)+\int_{\mathbf{X}} p(d \xi \mid x, a, b) u(\xi)
$$

for all $x \in \mathbf{X}, a \in \mathbf{A}, b \in \mathbf{B}$.
Let $\Pi=\left(\pi_{n}\right) \in \mathbf{E}^{\infty}, P=\left(\rho_{n}\right) \in \mathbf{F}^{\infty}$. If $V_{\Pi P}^{N}$ exists, then we get

$$
V_{\Pi P}^{N}=\pi_{0} \rho_{0} k+\sum_{j=1}^{N} \pi_{0} \rho_{0} p \cdots p \pi_{j} \rho_{j} k
$$

For $\pi \in \mathbf{E}, \rho \in \mathbf{F}$ we put $(\pi \rho p)^{n}:=\pi \rho p(\pi \rho p)^{n-1}$ where $(\pi \rho p)^{0}$ denotes the identity. Let $\vartheta \in(0,1)$. We set for every $\pi \in \mathbf{E}, \rho \in \mathbf{F}, x \in \mathbf{X}$, and $Y \in \sigma_{\mathbf{X}}$

$$
Q_{\vartheta, \pi, \rho}(Y \mid x):=(1-\vartheta) \sum_{n=0}^{\infty} \vartheta^{n}(\pi \rho p)^{n} \mathbf{I}_{Y}(x)
$$

where $\mathbf{I}_{Y}$ is the characteristic function of the set $Y$.
We remark that for a stationary strategy pair $\left(\pi^{\infty}, \rho^{\infty}\right)$ the transition probability $Q_{\vartheta, \pi, \rho}$ is a resolvent of the corresponding Markov chain.

Assumption 3.1 There are: a nontrivial measure $\mu$ on $\sigma_{\mathbf{X}}$; a set $C \in$ $\sigma_{\mathbf{X}}$; a $\sigma_{\mathbf{X}}$-measurable function $W \geq 1$; and constants $\vartheta \in(0,1), \alpha \in$ $(0,1)$, and $\beta \in \mathbb{R}$, with the following properties:
(a)

$$
Q_{\vartheta, \pi, \rho} \geq \mathbf{I}_{C} \cdot \mu
$$

for all $\pi \in \mathbf{E}$ and $\rho \in \mathbf{F}$,
(b)

$$
p W \leq \alpha W+\mathbf{I}_{C} \beta
$$

(c)

$$
\sup _{x \in \mathbf{X}, a \in \boldsymbol{A}(x), b \in \boldsymbol{B}(x)} \frac{|k(x, a, b)|}{W(x)}<\infty .
$$

Assumption 3.1 (a) means that $C$ is a "petite set", (b) is called "geometric drift towards $C$ " (see Meyn and Tweedie [10]). We assume in this paper that Assumption 3.1 is satisfied.

Lemma 3.2 There are a $\sigma_{\mathbf{X}}$-measurable function $V$ with $1 \leq W \leq$ $V \leq W+$ const, and a constant $\lambda \in(0,1)$ with

$$
\begin{equation*}
Q_{\vartheta, \pi, \rho} V \leq \lambda V+\mathbf{I}_{C} \cdot \mu V \tag{3.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\vartheta p V \leq \lambda V . \tag{3.2}
\end{equation*}
$$

Proof: Without loss of generality we assume $\beta>0$. Let $\beta^{\prime}:=\frac{\vartheta}{1-\vartheta} \beta$, $W^{\prime}:=W+\beta^{\prime}$, and $\alpha^{\prime}:=\frac{\beta^{\prime}+\alpha}{\beta^{\prime}+1}$. Then it holds that $\alpha^{\prime} \in(\alpha, 1)$ and

$$
\begin{align*}
p W^{\prime} & =p W+\beta^{\prime} \\
& \leq \alpha W+\beta^{\prime}+\beta \mathbf{I}_{C} \\
& \leq \alpha^{\prime} W-\left(\alpha^{\prime}-\alpha\right) W+\alpha^{\prime} \beta^{\prime}+\left(1-\alpha^{\prime}\right) \beta^{\prime}+\beta \mathbf{I}_{C} \\
& \leq \alpha^{\prime} W^{\prime}-\left(\alpha^{\prime}-\alpha\right)+\left(1-\alpha^{\prime}\right) \beta^{\prime}+\beta \mathbf{I}_{C} \\
& =\alpha^{\prime} W^{\prime}+\beta^{\prime}+\alpha-\alpha^{\prime}\left(\beta^{\prime}+1\right)+\beta \mathbf{I}_{C} \\
& =\alpha^{\prime} W^{\prime}+\beta \mathbf{I}_{C} . \tag{3.3}
\end{align*}
$$

Now let $W^{\prime \prime}:=W^{\prime}-\beta^{\prime} \mathbf{I}_{C}=W+\beta^{\prime}\left(1-\mathbf{I}_{C}\right)$. Then we get from (3.3)

$$
\begin{align*}
p\left(W^{\prime \prime}+\beta^{\prime} \mathbf{I}_{C}\right) & =p W^{\prime} \\
& \leq \alpha^{\prime} W^{\prime}+\beta \mathbf{I}_{C} \\
& =\alpha^{\prime} W^{\prime \prime}+\alpha^{\prime} \beta^{\prime} \mathbf{I}_{C}+\beta \mathbf{I}_{C} \\
& =\alpha^{\prime} W^{\prime \prime}+\alpha^{\prime} \beta^{\prime} \mathbf{I}_{C}+\frac{1-\vartheta}{\vartheta} \beta^{\prime} \mathbf{I}_{C} \\
& =\alpha^{\prime} W^{\prime \prime}+\frac{\alpha^{\prime} \vartheta+1-\vartheta}{\vartheta} \beta^{\prime} \mathbf{I}_{C} \\
& \leq \alpha^{\prime} W^{\prime \prime}+\frac{\beta^{\prime}}{\vartheta} \mathbf{I}_{C} \tag{3.4}
\end{align*}
$$

We put $\alpha^{\prime \prime}:=\frac{1-\vartheta}{1-\alpha^{\prime} \vartheta}$. Then it holds that $\alpha^{\prime}=\frac{\alpha^{\prime \prime}+\vartheta-1}{\alpha^{\prime \prime} \vartheta}$. For $\beta^{\prime \prime}:=\alpha^{\prime \prime} \beta^{\prime}$ it follows:

$$
p W^{\prime \prime} \leq \frac{\alpha^{\prime \prime}+\vartheta-1}{\alpha^{\prime \prime} \vartheta} W^{\prime \prime}-\frac{\beta^{\prime \prime}}{\alpha^{\prime \prime}} p \mathbf{I}_{C}+\frac{\beta^{\prime \prime}}{\alpha^{\prime \prime} \vartheta} \mathbf{I}_{C}
$$

Hence,

$$
\alpha^{\prime \prime} \vartheta p W^{\prime \prime} \leq\left(\alpha^{\prime \prime}+\vartheta-1\right) W^{\prime \prime}-\vartheta \beta^{\prime \prime} p \mathbf{I}_{C}+\beta^{\prime \prime} \mathbf{I}_{C}
$$

Then

$$
(1-\vartheta) W^{\prime \prime} \leq \alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}-\vartheta p\left(\alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}\right)
$$

This implies

$$
(1-\vartheta) W^{\prime \prime} \leq \alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}-\vartheta \pi \rho p\left(\alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}\right)
$$

for every $\pi \in \mathbf{E}, \rho \in \mathbf{F}$. Hence,

$$
\begin{align*}
Q_{\vartheta, \pi, \rho} W^{\prime \prime}= & \sum_{n=0}^{\infty}(1-\vartheta) \vartheta^{n}(\pi \rho p)^{n} W^{\prime \prime} \\
\leq & \sum_{n=0}^{\infty} \vartheta^{n}(\pi \rho p)^{n}\left(\alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}\right) \\
& -\sum_{n=1}^{\infty} \vartheta^{n}(\pi \rho p)^{n}\left(\alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C}\right) \\
= & \alpha^{\prime \prime} W^{\prime \prime}+\beta^{\prime \prime} \mathbf{I}_{C} \tag{3.5}
\end{align*}
$$

We choose $\vartheta^{\prime} \in(\vartheta, 1)$ and set $\gamma:=\max \left\{\frac{\beta^{\prime \prime}}{\mu(\mathbf{X})}, \frac{\beta^{\prime}}{\vartheta^{\prime}-\vartheta}\right\}, \lambda^{\prime}:=\frac{\alpha^{\prime \prime}+\gamma}{1+\gamma}, \lambda:=$ $\max \left\{\lambda^{\prime}, \vartheta^{\prime}\right\}$. It follows that $\alpha^{\prime \prime}<\lambda^{\prime} \leq \lambda<1$ and $\lambda^{\prime}-\alpha^{\prime \prime}=\left(1-\lambda^{\prime}\right) \gamma$. Hence,

$$
\begin{equation*}
\left(\lambda-\alpha^{\prime \prime}\right) W^{\prime \prime} \geq \lambda^{\prime}-\alpha^{\prime \prime} \geq\left(1-\lambda^{\prime}\right) \gamma \geq(1-\lambda) \gamma \tag{3.6}
\end{equation*}
$$

We put $V:=W^{\prime \prime}+\gamma$. Obviously, $V \geq W^{\prime \prime} \geq 1$ and $V \geq \gamma$. Then it follows

$$
\begin{aligned}
Q_{\vartheta, \pi, \rho} V & =Q_{\vartheta, \pi, \rho} W^{\prime \prime}+\gamma \\
& \leq \alpha^{\prime \prime} W^{\prime \prime}+\mathbf{I}_{C} \cdot \beta^{\prime \prime}+\gamma \\
& \leq \alpha^{\prime \prime} W^{\prime \prime}+\mathbf{I}_{C} \cdot \gamma \mu(\mathbf{X})+\gamma \\
& \leq \alpha^{\prime \prime} W^{\prime \prime}+\mathbf{I}_{C} \cdot \mu V+\gamma \\
& \leq \alpha^{\prime \prime} W^{\prime \prime}+\mathbf{I}_{C} \cdot \mu V+\left(\lambda-\alpha^{\prime \prime}\right) W^{\prime \prime}+\lambda \gamma(\text { see }(3.6)) \\
& =\lambda\left(W^{\prime \prime}+\gamma\right)+\mathbf{I}_{C} \cdot \mu V \\
& =\lambda V+\mathbf{I}_{C} \cdot \mu V
\end{aligned}
$$

Hence, (3.1 ) is proved.
From $\gamma \geq \frac{\beta^{\prime}}{\vartheta^{\prime}-\vartheta}$ it follows

$$
\begin{equation*}
\vartheta^{\prime} \gamma \geq \vartheta \gamma+\beta^{\prime} . \tag{3.7}
\end{equation*}
$$

Then

$$
\begin{aligned}
\vartheta p V & =\vartheta p W^{\prime \prime}+\vartheta \gamma \\
& \leq \alpha^{\prime} \vartheta W^{\prime \prime}+\beta^{\prime}+\vartheta \gamma(\text { see }(3.4)) \\
& \leq \alpha^{\prime} \vartheta W^{\prime \prime}+\vartheta^{\prime} \gamma(\text { see }(3.7)) \\
& \leq \vartheta^{\prime}\left(W^{\prime \prime}+\gamma\right) \\
& =\vartheta^{\prime} V \\
& \leq \lambda V .
\end{aligned}
$$

Hence, (3.2 ) is also proved.

## 4 Properties of Stationary Strategy Pairs

For a function $u: \mathbf{X} \rightarrow \mathbb{R}$ we put $\|u\|_{V}:=\sup _{x \in \mathbf{X}} \frac{|u(x)|}{V(x)}$. Furthermore, we denote by $\mathfrak{V}$ the set of all $\sigma_{\mathbf{X}}$-measurable functions $u$ with $\|u\|_{V}<\infty$. In the following we will assume that on $\mathfrak{V}$ that metric is given which is induced by the weighted supremum norm $\|\cdot\|_{V}$. Then $\mathfrak{V}$ is complete.
Lemma $4.1\left\|\sup _{n \in \mathbb{N}, \pi \in \mathbf{E}, \rho \in \mathbf{F}}(\pi \rho p)^{n} V\right\|_{V}<\infty$.
Proof: From Assumption 3.1(b) it follows that

$$
(\pi \rho p)^{n} W \leq \alpha^{n} W+\frac{1}{1-\alpha} \beta .
$$

By Lemma 3.2 we get

$$
(\pi \rho p)^{n} V \leq(\pi \rho p)^{n} W+\text { const } \leq \alpha^{n} W+\text { const }^{\prime} \leq \alpha^{n} V+\text { const }^{\prime}
$$

The statement is implied by this.
Let $T_{w}$ be the operator given by

$$
T_{w} u(x, a, b):=(1-\vartheta)(\vartheta k(x, a, b)+w(x))+\vartheta p u(x, a, b)
$$

for all $u \in \mathfrak{V}, x \in \mathbf{X}, a \in \mathbf{A}, b \in \mathbf{B}$. We note that $T_{w}$ has essentially the same structure as the cost operator $T$ used in stochastic dynamic
programming and stochastic game theory. This implies that some of our proofs are very similar to known proofs. Therefore we will restrict ourselves to a few remarks in these cases. (A very good exposition of basic ideas and recent developments in stochastic dynamic programming can be found in the books of Hernández- Lerma and Lasserre [1], [2].) Obviously,

$$
\begin{equation*}
T_{w} u=(1-\vartheta) \vartheta T\left(\frac{u}{1-\vartheta}\right)+(1-\vartheta) w . \tag{4.8}
\end{equation*}
$$

Lemma 4.2 Let $w \in \mathfrak{V}, \pi \in \mathbf{E}, \rho \in \mathbf{F}$. Then the functional equation

$$
\begin{equation*}
u=\pi \rho T_{w} u \tag{4.9}
\end{equation*}
$$

has a unique solution $u_{w}=S_{\pi \rho} w \in \mathfrak{V}$ and it holds:

$$
\begin{equation*}
S_{\pi \rho} w=\lim _{n \rightarrow \infty}\left(\pi \rho T_{w}\right)^{n} u=(1-\vartheta) \sum_{n=0}^{\infty} \vartheta^{n}(\pi \rho p)^{n}(\vartheta \pi \rho k+w) \tag{4.10}
\end{equation*}
$$

for every $u \in \mathfrak{V}$.
Proof: We note that $\pi \rho T_{w} \mathfrak{V} \subseteq \mathfrak{V}$. From (3.2) it follows that $\pi \rho T_{w}$ is contracting on $\mathfrak{V}$ with modulus $\lambda$. The rest of the proof follows by Banach's Fixed Point Theorem.

We define a new operator $S_{\gamma, \pi, \rho}$ by

$$
\begin{equation*}
S_{\gamma, \pi, \rho} w:=-\left(1-\mathbf{I}_{C}\right) \gamma+S_{\pi \rho} w-\mathbf{I}_{C} \mu w \tag{4.11}
\end{equation*}
$$

for $\pi \in \mathbf{E}, \rho \in \mathbf{F}, w \in \mathfrak{V}$ where $S_{\pi \rho}$ is the operator defined by the functional equation (4.9). The following lemma gives some properties of this operator.

Lemma 4.3 (a) $S_{\gamma, \pi, \rho} \mathfrak{V} \subseteq \mathfrak{V}$.
(b) $S_{\gamma, \pi, \rho}$ is isotonic.
(c) $S_{\gamma, \pi, \rho}$ is contracting.

Proof: (a) is obvious.
(b) Using (4.10) we get

$$
\begin{align*}
S_{\gamma, \pi, \rho} w= & -\left(1-\mathbf{I}_{C}\right) \gamma+(1-\vartheta) \sum_{n=0}^{\infty} \vartheta^{n}(\pi \rho p)^{n}(\vartheta \pi \rho k+w)-\mathbf{I}_{C} \mu w \\
= & -\left(1-\mathbf{I}_{C}\right) \gamma+(1-\vartheta) \sum_{n=0}^{\infty} \vartheta^{n+1}(\pi \rho p)^{n} \pi \rho k \\
& +\left(Q_{\vartheta, \pi, \rho}-\mathbf{I}_{C} \mu\right) w \tag{4.12}
\end{align*}
$$

The statement follows from Assumption 3.1 (a).
(c) By Lemma 3.2 and (4.12) we get for $u, v \in \mathfrak{V}$

$$
\begin{align*}
\left|S_{\gamma, \pi, \rho} u-S_{\gamma, \pi, \rho} v\right| & =\left|\left(Q_{\vartheta, \pi, \rho}-\mathbf{I}_{C} \mu\right)(u-v)\right| \\
& \leq\left(Q_{\vartheta, \pi, \rho}-\mathbf{I}_{C} \mu\right) V\|u-v\|_{V} \\
& \leq \lambda V\|u-v\|_{V} . \square \tag{4.13}
\end{align*}
$$

Lemma 4.4 The operator $S_{\gamma, \pi, \rho}$ has in $\mathfrak{V}$ a unique fixed point $u_{\gamma, \pi, \rho}$. $\mu u_{\gamma, \pi, \rho}$ is continuous and non-increasing in $\gamma$.

Proof: The existence and uniqueness of the fixed point follows from Lemma 4.3 by Banach's Fixed Point Theorem. From $S_{\gamma, \pi, \rho} v \geq S_{\gamma^{\prime}, \pi, \rho} v$ for $\gamma \leq \gamma^{\prime}$, and the isotonicity of $S_{\gamma, \pi, \rho}$ it follows that $u_{\gamma, \pi, \rho} \geq u_{\gamma^{\prime}, \pi, \rho}$. Hence, $\mu u_{\gamma, \pi, \rho} \geq \mu u_{\gamma^{\prime}, \pi, \rho}$. Furthermore, for arbitrary $\gamma, \gamma^{\prime}$

$$
\begin{aligned}
\left|u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right| & =\left|\left(1-\mathbf{I}_{C}\right)\left(\gamma^{\prime}-\gamma\right)+\left(Q_{\vartheta, \pi, \rho}-\mathbf{I}_{C} \mu\right)\left(u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right)\right| \\
& \leq\left|\gamma-\gamma^{\prime}\right| V+\lambda\left\|u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right\|_{V} V
\end{aligned}
$$

Hence,

$$
\left\|u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right\|_{V} \leq\left|\gamma-\gamma^{\prime}\right|+\lambda\left\|u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right\|_{V}
$$

and

$$
\begin{aligned}
\left|\mu u_{\gamma, \pi, \rho}-\mu u_{\gamma^{\prime}, \pi, \rho}\right| & \leq\left\|u_{\gamma, \pi, \rho}-u_{\gamma^{\prime}, \pi, \rho}\right\|_{V} \mu V \\
& \leq \frac{\left|\gamma-\gamma^{\prime}\right|}{1-\lambda} \mu V .
\end{aligned}
$$

Theorem 4.5 There exists a constant $g$ and $v \in \mathfrak{V}$ such that

$$
\begin{equation*}
g+v=\pi \rho k+\pi \rho p v \tag{4.14}
\end{equation*}
$$

It holds:

$$
g=\Phi_{\pi^{\infty} \rho^{\infty}} .
$$

Proof: From Lemma 4.4 it follows that there is a $\gamma^{*}$ with $\gamma^{*}=\mu u_{\gamma^{*}, \pi, \rho}$. Hence,

$$
\begin{align*}
u_{\gamma^{*}, \pi, \rho} & =S_{\gamma^{*}, \pi, \rho} u_{\gamma^{*}, \pi, \rho} \\
& =-\left(1-\mathbf{I}_{C}\right) \gamma^{*}+S_{\pi \rho} u_{\gamma^{*}, \pi, \rho}-\mathbf{I}_{C} \mu u_{\gamma^{*}, \pi, \rho} \\
& =S_{\pi \rho} u_{\gamma^{*}, \pi, \rho}-\gamma^{*} \tag{4.15}
\end{align*}
$$

Let $w^{*}:=u_{\gamma^{*}, \pi, \rho}$. If we put $w=w^{*}$ in (4.9), then we get

$$
S_{\pi \rho} w^{*}=(1-\vartheta)\left(\vartheta \pi \rho k+w^{*}\right)+\vartheta \pi \rho p S_{\pi \rho} w^{*} .
$$

It follows by (4.15) that

$$
w^{*}+\gamma^{*}=(1-\vartheta)\left(\vartheta \pi \rho k+w^{*}\right)+\vartheta \pi \rho p\left(w^{*}+\gamma^{*}\right) .
$$

Therefore,

$$
\vartheta w^{*}+(1-\vartheta) \gamma^{*}=(1-\vartheta) \vartheta \pi \rho k+\vartheta \pi \rho p w^{*} .
$$

For $g=\frac{\gamma^{*}}{\vartheta}, v=\frac{w^{*}}{1-\vartheta}$ we get (4.14). From (4.14) it follows

$$
N g=\sum_{n=0}^{N-1}(\pi \rho p)^{n} \pi \rho k+(\pi \rho p)^{N} v-v
$$

If we consider Lemma 4.1 we get

$$
g=\lim _{N \rightarrow \infty} \frac{1}{N} \sum_{n=0}^{N-1}(\pi \rho p)^{n} \pi \rho k=\Phi_{\pi^{\infty} \rho^{\infty}} .
$$

## 5 Existence of optimal stationary strategies

We give first a lemma which concerns a certain auxiliary one-stage game. The results of this lemma are well-known and can be derived, for instance, from the results in [12].

Lemma 5.1 Let $u: \mathbf{X} \times \mathbf{A} \times \mathbf{B} \rightarrow \mathbb{R}$ a $\sigma_{\mathbf{X} \times \mathbf{A} \times \mathbf{B} \text {-measurable function }}$ with $\sup _{x \in \mathbf{X}, a \in \boldsymbol{A}(x), b \in \boldsymbol{B}(x)} \frac{|u(x, a, b)|}{V(x)}<\infty$. Then it holds:
(a) $\inf _{\pi \in \mathbf{E}} \sup _{\rho \in \mathbf{F}} \pi \rho u=\sup _{\rho \in \mathbf{F}} \inf _{\pi \in \mathbf{E}} \pi \rho u \in \mathfrak{V}$.
(b) There are $\pi^{*} \in \mathbf{E}, \rho^{*} \in \mathbf{F}$ with $\pi^{*} \rho u \leq \pi^{*} \rho^{*} u \leq \pi \rho^{*} u$ for all $\pi \in \mathbf{E}, \rho \in \mathbf{F}$.

For a function $v: \mathbf{X} \times \mathbf{A} \rightarrow \mathbb{R}(v: \mathbf{X} \times \mathbf{B} \rightarrow \mathbb{R})$ we put $L v:=\inf _{\pi \in \mathbf{E}} \pi v$ $\left(U v:=\sup _{\rho \in \mathbf{F}} \rho v\right)$. We can now prove the following lemma concerning an auxiliary functional equation.

Lemma 5.2 The functional equation

$$
\begin{align*}
u & =\inf _{\pi \in \mathbf{E}} \sup _{\rho \in \mathbf{F}}\{(1-\vartheta)(\vartheta \pi \rho k+w)+\vartheta \pi \rho p u\} \\
& =L U T_{w} u \\
& =(1-\vartheta) \vartheta L U T\left(\frac{u}{1-\vartheta}\right)+(1-\vartheta) w \tag{5.16}
\end{align*}
$$

has for every $w \in \mathfrak{V}$ a unique solution $u^{*}=: S w$ in $\mathfrak{V}$.
Proof: Let $w \in \mathfrak{V}$. Then it follows from Lemma 5.1 that $L U T_{w} \mathfrak{V} \subseteq \mathfrak{V}$. Because $\pi \rho T_{w}$ is contracting on $\mathfrak{V}$, it holds for $u, v \in \mathfrak{V}$ :

$$
\pi \rho T_{w} u \leq \pi \rho T_{w} v+\lambda\|u-v\|_{V} V
$$

Since $L$ and $U$ are isotonic it follows:

$$
L U T_{w} u \leq L U T_{w} v+\lambda\|u-v\|_{V} V .
$$

Because $u$ and $v$ can be interchanged, we get that $L U T_{w}$ is also contracting. The statement follows by Banach's Fixed Point Theorem.

In the following lemma $S_{\pi \rho}$ and $S$ are the operators defined by the functional equations (4.9) and (5.16).

Lemma 5.3 For every $w \in \mathfrak{V}$ there are $\pi^{*} \in \mathbf{E}, \rho^{*} \in \mathbf{F}$ with

$$
\begin{equation*}
S_{\pi^{*}, \rho} w \leq S w \leq S_{\pi, \rho^{*}} w \tag{5.17}
\end{equation*}
$$

for all $\pi \in \mathbf{E}, \rho \in \mathbf{F}$. Furthermore,

$$
\begin{equation*}
S w:=\inf _{\pi \in \mathbf{E}} \sup _{\rho \in \mathbf{F}} S_{\pi \rho} w \tag{5.18}
\end{equation*}
$$

Proof: It follows from Lemma 5.1 that there are $\pi^{*} \in \mathbf{E}, \rho^{*} \in \mathbf{F}$ such that

$$
\begin{align*}
\pi^{*} \rho T\left(\frac{u_{w}}{1-\vartheta}\right) & \leq \operatorname{LUT}\left(\frac{u_{w}}{1-\vartheta}\right) \\
& \leq \pi \rho^{*} T\left(\frac{u_{w}}{1-\vartheta}\right) \tag{5.19}
\end{align*}
$$

where $u_{w}=S w$. Hence,

$$
\begin{equation*}
\pi^{*} \rho T_{w} u_{w} \leq L U T_{w} u_{w}=u_{w} \leq \pi \rho^{*} T_{w} u_{w} \tag{5.20}
\end{equation*}
$$

for all $\pi \in \mathbf{E}, \rho \in \mathbf{F}$. Assume that

$$
\begin{equation*}
\left(\pi^{*} \rho T_{w}\right)^{n} u_{w} \leq u_{w} \leq\left(\pi \rho^{*} T_{w}\right)^{n} u_{w} \tag{5.21}
\end{equation*}
$$

for $n \in \mathbb{N}$. Then it follows from (5.20) that

$$
\begin{equation*}
u_{w} \leq \pi \rho^{*} T_{w}\left(\left(\pi \rho^{*} T_{w}\right)^{n} u_{w}=\left(\pi \rho^{*} T_{w}\right)^{n+1} u_{w} .\right. \tag{5.22}
\end{equation*}
$$

Analogously,

$$
\begin{equation*}
u_{w} \geq\left(\pi^{*} \rho T_{w}\right)^{n+1} u_{w} \tag{5.23}
\end{equation*}
$$

From (5.22) and (5.23 ) it follows by mathematical induction that (5.21) holds for all $n \in \mathbb{N}$. For $n \rightarrow \infty$ we get (5.17). (5.18) follows immediately from (5.17).

We define a new operator $S_{\gamma}$ by

$$
S_{\gamma} w:=-\left(1-\mathbf{I}_{C}\right) \gamma+S w-\mathbf{I}_{C} \mu w
$$

for $\pi \in \mathbf{E}, \rho \in \mathbf{F}, w \in \mathfrak{V}, \gamma \in \mathbb{R}$. The following lemma gives some properties of this operator.

Lemma 5.4 (a) $S_{\gamma} \mathfrak{V} \subseteq \mathfrak{V}$.
(b) $S_{\gamma}$ is isotonic.
(c) $S_{\gamma}$ is contracting with modulus $\lambda$.
(d) $S_{\gamma}$ has in $\mathfrak{V}$ a unique fixed point $v_{\gamma}$. It holds $\lim _{n \rightarrow \infty}\left(S_{\gamma}\right)^{n} u=v_{\gamma}$ for every $u \in \mathfrak{V}$. Moreover, $v_{\gamma}$ is isotonic and continuous in $\gamma$.

Proof: (a) is obvious.
(b) From (4.11) and (5.18) it follows that

$$
S_{\gamma} w=\inf _{\pi \in \mathbf{E}} \sup _{\rho \in \mathbf{F}} S_{\gamma, \pi, \rho} w
$$

By Lemma 4.3 we get the statement.
(c) Let $w^{\prime}, w^{\prime \prime} \in \mathfrak{V}$. By Lemma 5.3 it follows that there are $\pi^{\prime \prime} \in \mathbf{E}$, $\rho^{\prime} \in \mathbf{F}$, such that

$$
\begin{gathered}
S w^{\prime} \leq S_{\pi, \rho^{\prime}} w^{\prime} \\
S w^{\prime \prime} \geq S_{\pi^{\prime \prime}, \rho} w^{\prime \prime}
\end{gathered}
$$

for all $\pi \in \mathbf{E}, \rho \in \mathbf{F}$. Hence,

$$
\begin{aligned}
S_{\gamma} w^{\prime}-S_{\gamma} w^{\prime \prime}= & -\left(1-\mathbf{I}_{C}\right) \gamma+S w^{\prime}-\mathbf{I}_{C} \mu w^{\prime} \\
& -\left(-\left(1-\mathbf{I}_{C}\right) \gamma+S w^{\prime \prime}-\mathbf{I}_{C} \mu w^{\prime \prime}\right) \\
\leq & -\left(1-\mathbf{I}_{C}\right) \gamma+S_{\pi^{\prime \prime}, \rho^{\prime}} w^{\prime}-\mathbf{I}_{C} \mu w^{\prime} \\
& -\left(-\left(1-\mathbf{I}_{C}\right) \gamma+S_{\pi^{\prime \prime}, \rho^{\prime}} w^{\prime \prime}-\mathbf{I}_{C} \mu w^{\prime \prime}\right) \\
= & S_{\gamma, \pi^{\prime \prime}, \rho^{\prime}} w^{\prime}-S_{\gamma, \pi^{\prime \prime}, \rho^{\prime}} w^{\prime \prime} \\
\leq & \lambda V\left\|w^{\prime}-w^{\prime \prime}\right\|_{V}
\end{aligned}
$$

since $S_{\gamma, \pi^{\prime \prime}, \rho^{\prime}}$ is contracting (see Lemma 4.3). Because $w^{\prime}$ and $w^{\prime \prime}$ can be interchanged, we get the statement.
(d) The existence of a unique fixed point $v_{\gamma} \in \mathfrak{V}$ and $\lim _{n \rightarrow \infty}\left(S_{\gamma}\right)^{n} u=v_{\gamma}$ for every $u \in \mathfrak{V}$ follows from Banach's Fixed Point Theorem. For $\gamma^{\prime} \leq \gamma$ it holds

$$
S_{\gamma} w \leq S_{\gamma^{\prime}} w=S_{\gamma} w+\left(1-\mathbf{I}_{C}\right)\left(\gamma-\gamma^{\prime}\right) \leq S_{\gamma} w+\left(\gamma-\gamma^{\prime}\right) V
$$

Assume that for $n>1$

$$
S_{\gamma}^{n-1} v_{\gamma^{\prime}} \leq v_{\gamma^{\prime}} \leq S_{\gamma}^{n-1} v_{\gamma^{\prime}}+\frac{\gamma-\gamma^{\prime}}{1-\lambda} V
$$

Then it follows

$$
\begin{gathered}
S_{\gamma}^{n} v_{\gamma^{\prime}} \leq S_{\gamma^{\prime}} S_{\gamma}^{n-1} v_{\gamma^{\prime}} \leq S_{\gamma^{\prime}} v_{\gamma^{\prime}}=v_{\gamma^{\prime}} \leq S_{\gamma^{\prime}}\left(S_{\gamma}^{n-1} v_{\gamma^{\prime}}+\frac{\gamma-\gamma^{\prime}}{1-\lambda} V\right) \\
\leq S_{\gamma}\left(S_{\gamma}^{n-1} v_{\gamma^{\prime}}+\frac{\gamma-\gamma^{\prime}}{1-\lambda} V\right)+\left(\gamma-\gamma^{\prime}\right) V \\
\leq S_{\gamma}^{n} v_{\gamma^{\prime}}+\frac{\lambda\left(\gamma-\gamma^{\prime}\right)}{1-\lambda} V+\left(\gamma-\gamma^{\prime}\right) V(\text { see }(\mathrm{c}))
\end{gathered}
$$

$$
=S_{\gamma}^{n} v_{\gamma^{\prime}}+\frac{\gamma-\gamma^{\prime}}{1-\lambda} V
$$

Hence, by mathematical induction we find that this inequality holds for all $n \in \mathbb{N}$. For $n \rightarrow \infty$ it follows

$$
v_{\gamma} \leq v_{\gamma^{\prime}} \leq v_{\gamma}+\frac{\gamma-\gamma^{\prime}}{1-\lambda} V
$$

The rest of the statement is implied by this.
Theorem 5.5 There are $g=$ const and $v \in \mathfrak{V}$ with

$$
\begin{equation*}
g+v=L U T v \tag{5.24}
\end{equation*}
$$

It holds

$$
g=\inf _{\Pi \in \mathbf{E}^{\infty}} \sup _{P \in \mathbf{F}^{\infty}} \Phi_{\Pi P}
$$

Furthermore, there is an optimal stationary strategy pair.
Proof: From Lemma 5.4 it follows that $\mu v_{\gamma}$ is non-increasing in $\gamma$. Therefore, there is a $\gamma^{*}$ with $\gamma^{*}=\mu v_{\gamma^{*}}$.

$$
\begin{align*}
v_{\gamma^{*}} & =S_{\gamma^{*}} v_{\gamma^{*}} \\
& =-\left(1-\mathbf{I}_{C}\right) \gamma^{*}+S v_{\gamma^{*}}-\mathbf{I}_{C} \mu v_{\gamma^{*}} \\
& =S v_{\gamma^{*}}-\gamma^{*} \tag{5.25}
\end{align*}
$$

Let $w^{*}:=v_{\gamma^{*}}$. If we put $w=w^{*}$ in (5.16) then we get

$$
S w^{*}=L U\left((1-\vartheta)\left(\vartheta k+w^{*}\right)+\vartheta p S w^{*}\right)
$$

It follows by (5.25)

$$
w^{*}+\gamma^{*}=L U\left((1-\vartheta)\left(\vartheta k+w^{*}\right)+\vartheta p\left(w^{*}+\gamma^{*}\right)\right)
$$

Therefore,

$$
\vartheta w^{*}+(1-\vartheta) \gamma^{*}=L U\left((1-\vartheta) \vartheta k+\vartheta p w^{*}\right)
$$

For $g=\frac{\gamma^{*}}{\vartheta}, v=\frac{w^{*}}{1-\vartheta}$ we get (5.24).
From (5.24) and Lemma 5.1 it follows that there are $\pi^{*} \in \mathbf{E}, \rho^{*} \in \mathbf{F}$, with

$$
\pi^{*} \rho_{n} T v_{\gamma^{*}}-g \leq v_{\gamma^{*}} \leq \pi_{n} \rho^{*} T v_{\gamma^{*}}+\varepsilon-g
$$

for all $\Pi=\left(\pi_{n}\right) \in \mathbf{E}^{\infty}, P=\left(\rho_{n}\right) \in \mathbf{F}^{\infty}$. It follows

$$
\begin{array}{r}
\quad \pi^{*} \rho_{0} T \pi^{*} \rho_{1} T \cdots \pi^{*} \rho_{N} T v_{\gamma^{*}}-(N+1) g \\
\leq \quad v_{\gamma^{*}} \leq \pi_{0} \rho^{*} T \pi_{1} \rho^{*} T \cdots \pi_{N} \rho^{*} T v_{\gamma^{*}}-(N+1) g
\end{array}
$$

For $N \rightarrow \infty$ we get

$$
\Phi_{\Pi \rho^{* \infty}} \leq g \leq \Phi_{\pi^{* \infty} P}
$$

for all $\Pi \in \mathbf{E}^{\infty}, P \in \mathbf{F}^{\infty}$. This implies

$$
g=\inf _{\Pi \in \mathbf{E}^{\infty}} \sup _{P \in \mathbf{F}^{\infty}} \Phi_{\Pi P}
$$

and the optimality of $\left(\pi^{* \infty}, \rho^{* \infty}\right)$.
Heinz-Uwe Küenle
Brandenburgische Technische Universität Cottbus
Institut für Mathematik
PF 101344
D-03013 Cottbus
GERMANY
Phone: + 49 (0355) 693151
Fax: +49 (0355) 693164
kuenle@math.tu-cottbus.de

## References

[1] Hernández-Lerma, O.; Lasserre, J. B.: Discrete-Time Markov Control Processes: Basic Optimality Criteria. Applications of Mathematics 30. Springer-Verlag, New York, 1996
[2] Hernández-Lerma, O.; Lasserre, J. B.: Further Topics on Discrete-Time Markov Control Processes. Applications of Mathematics 42. Springer-Verlag, New York, 1999
[3] Küenle, H.-U.: Stochastische Spiele und Entscheidungsmodelle. Teubner-Texte zur Mathematik 89. Teubner-Verlag, Leipzig, 1986
[4] Küenle, H.-U.: Stochastic games with complete information and average cost criterion. Advances in Dynamic Games and Applications [edited by J.A. Filar, V. Gaitsgory, K. Mizukami] (Annals of the International Society of Dynamic Games, Vol. 5) Birkhäuser, Boston, 2000, 325-338
[5] Küenle, H.-U.: Equilibrium strategies in stochastic games with additive cost and transition structure. International Game Theory Review, 1, 1999, 131-147
[6] Küenle, H.-U.: On multichain Markov games. Annals of the International Society of Dynamic Games. Birkhäuser, to appear
[7] Maitra, A.; Sudderth, W.: Borel stochastic games with limsup payoff. Ann. Probab., 21, 1993, 861-885
[8] Maitra, A.; Sudderth, W.: Finitely additive and measurable stochastic games. Internat. J. Game Theory, 22, 1993, 201-223
[9] Maitra, A.; Sudderth, W.: Finitely additive stochastic games with Borel measurable payoffs. Internat. J. Game Theory, 27, 1998, 257-267
[10] Meyn, S. P.; Tweedie, R. L.: Markov Chains and Stochastic Stability. Communication and Control Engineering Series. SpringerVerlag, London, 1993
[11] Neveu, J.: Mathematical Foundations of the Calculus of Probability. Holden-Day, San Francisco 1965
[12] Nowak, A. S.: Minimax selection theorems. J. Math. Anal. Appl. 103, 1984, 106-116.
[13] Nowak, A. S.: Zero-sum average payoff stochastic games with general state space. Games and Econ. Behavior 7, 1994, 221-232
[14] Nowak, A. S.: Optimal strategies in a class of zero-sum ergodic stochastic games.Math. Meth. Oper. Res. 50, 1999, 399-419
[15] Rieder, U.: Average optimality in Markov games with general state space. Proc. 3rd International Conf. on Approximation and Optimization, Puebla, 1995


[^0]:    ${ }^{*}$ Invited article

